

Maximal height statistics for $1/f^\alpha$ signals

G. Györgyi,^{*} N. R. Moloney,[†] K. Ozogány,[‡] and Z. Rácz[§]

Institute for Theoretical Physics - HAS Research Groups, Eötvös University, Pázmány sétány 1/a, 1117 Budapest, Hungary

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Numerical and analytical results are presented for the maximal relative height distribution of stationary periodic Gaussian signals (one-dimensional interfaces) displaying a $1/f^\alpha$ power spectrum. For $0 \leq \alpha < 1$ (regime of decaying correlations), we observe that the mathematically established limiting distribution (Fisher-Tippett-Gumbel distribution) is approached extremely slowly as the sample size increases. The convergence is rapid for $\alpha > 1$ (regime of strong correlations) and a highly accurate picture gallery of distribution functions can be constructed numerically. Analytical results can be obtained in the limit $\alpha \rightarrow \infty$ and, for large α , by perturbation expansion. Furthermore, using path integral techniques we derive a trace formula for the distribution function, valid for $\alpha = 2n$ even integer. From the latter we extract the small argument asymptote of the distribution function whose analytic continuation to arbitrary $\alpha > 1$ is found to be in agreement with simulations. Comparison of the extreme and roughness statistics of the interfaces reveals similarities in both the small and large argument asymptotes of the distribution functions.

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I. INTRODUCTION

Whereas the extreme value statistics (EVS) of independent and identically distributed (i.i.d.) random variables has been thoroughly understood for a long time [1–3], our knowledge about the EVS of correlated variables is less general. Many natural processes, like flood-water levels, meteorological parameters, and earthquake magnitudes [4–6], are, however, characterized by large variations, a phenomenon connected to long term correlations. Since extremal occurrences in physical quantities may be of great significance, it is essential to develop an understanding of EVS in the presence of correlations. The past few years have seen increased activity in this direction, with several particular cases worked out in detail. For example, extremal height fluctuations in (1+1)-dimensional Edwards-Wilkinson surfaces have been investigated recently [7,8], and a nontrivial distribution function, the Airy distribution, was found analytically for the stationary surface. Equivalently, considering the latter as a time signal, this result relates to maximal displacements in Brownian random walks. Other studies of surface fluctuations also demonstrate the effect of correlations on EVS, and several examples show that nontrivial EVS may emerge even in the simplest surface evolution models [9–14]. Remarkable connections have also been found between EVS and propagating front solutions, exploited in such problems as random fragmentation [15], directed polymers on Cayley trees [16], and random binary-tree searches [17]. Correlations have also been shown to play an important role in effecting extreme events in weather records [18,19]. To summarize, problems related to extremes regularly arise, and it is a fundamental question whether they obey a limit distribution characterizing i.i.d. variables, or some special, nontrivial, statistics emerges.

In order to develop an intuition about the effect of correlations, we shall consider here the EVS of periodic signals displaying Gaussian fluctuations with $1/f^\alpha$ power spectra. While we shall use the terminology of time signals, one-dimensional stationary interfaces may equally be imagined, with the same spatial spectrum, and periodic boundary conditions. Systems with $1/f^\alpha$ type fluctuations are abundant in nature, with examples ranging from voltage fluctuations in resistors [20], through temperature fluctuations in the oceans [21], to climatological temperature records [22], to the number of stocks traded daily [23]. In addition, most of these fluctuations appear to be Gaussian, thus our results may have relevance in answering questions about the probability of extreme events therein.

The $1/f^\alpha$ signals we consider are rather simple in the sense that they decompose into independent modes in Fourier space. The modes are not identically distributed, however, giving rise to temporal correlations, which are by now well understood (see Sec. II). Correlations are tuned by α , yielding signals with no correlations ($\alpha = 0$), decaying ($0 < \alpha < 1$), and diverging correlations ($1 \leq \alpha < \infty$). Thus $1/f^\alpha$ processes are also well suited for studying the effect of a wide range of correlations on extreme events in signals.

The central quantity we investigate is the maximum relative height (MRH), first studied in [24]. This is the highest peak of a signal over a given time interval T , measured from the average level. Specifically, for each realization of the signal, $h(t)$, the MRH is

$$h_m := \max_t h(t) - \overline{h(t)}, \quad (1)$$

where $\max_t h(t)$ is the peak of the signal and $\overline{h(t)}$ is its time average. The MRH, h_m , varies from realization to realization, and is therefore a random variable whose probability density function (PDF), denoted by $P(h_m)$, we would like to determine. The physical significance of h_m is obvious. For instance, in a corroding surface it gives the maximal depth of damage or, in general, it is the maximal peak of a surface. To

^{*}Electronic address: gyorgyi@glu.elte.hu

[†]Electronic address: moloney@general.elte.hu

[‡]Electronic address: ozogany@general.elte.hu

[§]Electronic address: racz@general.elte.hu

name another example, when natural water level fluctuations are considered, it is related to the necessary dam height.

Since the Fourier components of the signal are independent variables, it is relatively easy to generate h_m 's numerically and thereby obtain sufficient statistics for sampling $P(h_m)$ (see Sec. III). Scanning through $0 \leq \alpha < \infty$ reveals that $\alpha_c=1$ separates two regions with distinct behaviors in both the limiting functions and the convergence to them as the signal length ($0 \leq t \leq T$) tends to infinity. At $\alpha=0$, the signal is made up of i.i.d. variables and the EVS is governed by the Fisher-Tippett-Gumbel (FTG) distribution, which is one of the three possible limit distributions for i.i.d. variables in the traditional categorization [25,26]. In fact, this property extends to the whole $0 \leq \alpha < 1$ interval [27], where the correlations decay in a power-law fashion. Our results indicate that, at least in the $0 \leq \alpha < 0.5$ region, not only the limit distribution but the convergence to it closely follows the logarithmically slow convergence which characterizes $\alpha=0$ (Sec. IV). We find that the convergence further slows down in the $0.5 < \alpha < 1$ region and it remains an open question whether it is slower or not than logarithmic.

For $\alpha \geq 1$, the signal becomes rough, that is, the correlations diverge with signal length, and we find that the qualitative features of the EVS for $\alpha > 1$ are the same as in the $\alpha=2$ case (Sec. V), exactly solved by Comtet and Majumdar [7,8]. Namely, the divergent scale of the extreme values $\langle h_m \rangle \sim T^\beta$, where $\beta=(\alpha-1)/2$, is proportional to the scale of the fluctuations in the signal (square root of the roughness in interface language) and, furthermore, the large- and small-argument asymptotes of the limiting distribution functions are of similar type. In order to demonstrate these similarities, we study the generalized, higher order, random acceleration problem (α =even integer) in Sec. VI, and calculate the propagator of this process. Using this result, we develop a generalization of the trace formula (Sec. VII) which was instrumental in solving the $\alpha=2$ problem. It turns out that the trace formula can be written in a scaling form, which yields the scale of the MRH values (Sec. VIII) as well as, under a rather mild and natural assumption, the small-argument asymptote of the MRH distribution (Sec. IX). Our numerical evaluations of the distributions are all in excellent agreement with the analytical results.

Analytical results can also be obtained in the $\alpha \rightarrow \infty$ limit (Sec. V), where the lowest frequency mode determines the shape of the signal. We find that the MRH distribution has the functional form $\sim x \exp(-x^2)$. Corrections to the $\alpha \rightarrow \infty$ limit may be obtained by keeping the lowest frequency modes. With only three modes, a satisfactory description of the whole $\alpha \geq 6$ region can be obtained (Sec. X). Since both the $\alpha=2$ and $\alpha=\infty$ results suggest that the large-argument tail of the distribution takes the form $\sim x^\gamma \exp(-x^2)$, we checked this property for other α 's as well, and found it to be an excellent description for all $\alpha > 1$.

The common scaling properties of the maximal height and the root mean square height for $\alpha > 1$ lead us to compare the MRH distributions to the roughness distributions of $1/f^\alpha$ interfaces [28]. We find in Sec. XI that, in addition to the general shape of the PDFs, both the small and large argument asymptotes of these functions have analogous functional

forms provided the replacement $h_m \rightarrow (\text{roughness})^{1/2}$ is made. Similar conclusions can also be reached when $P(h_m)$ is compared with the distribution of maximal intensities [10].

Concluding remarks are collected in Sec. XII while details of the calculations of the generalized random acceleration process and of the large α expansion are given in Appendixes A and B, respectively.

II. GAUSSIAN PERIODIC $1/f^\alpha$ SIGNALS

We consider Gaussian periodic signals $h(t)=h(t+T)$ of length T . The probability density functional of $h(t)$ is given by

$$\mathcal{P}[h(t)] \sim e^{-S[h(t)]}, \quad (2)$$

where the effective action S can be formally defined in real space but, in practice, is defined through its Fourier representation

$$S[c_n; \alpha] = 2\lambda T^{1-\alpha} \sum_{n=1}^{N/2} n^\alpha |c_n|^2. \quad (3)$$

Here λ is a stiffness parameter which is set to $(2\pi)^\alpha/2$ hereafter (for the details and notation we follow [28]), and the c_n 's are the Fourier coefficients of $h(t)$

$$h(t) = \sum_{n=-N/2+1}^{N/2} c_n e^{2\pi i n t / T}, \quad (4)$$

where $c_n^* = c_{-n}$ and their phases (for $n \neq N/2$) are independent random variables uniformly distributed in the interval $[0, 2\pi]$, while $c_{N/2}$ is real. Since c_0 does not appear in the action (3) we can set the average of the signal to zero, i.e., $c_0=0$. Note that the cutoff introduced by N means that the time scale is not resolved below

$$\tau = T/N \quad (5)$$

and thus a measurement of $h(t)$ yields effectively N data points.

As one can see from Eqs. (2) and (3), the amplitudes of the Fourier modes are independent, Gaussian distributed variables — but they are not identically distributed. Indeed, the fluctuations increase with decreasing wave number, with power spectrum

$$\langle |c_n|^2 \rangle \propto \frac{1}{n^\alpha}, \quad (6)$$

as befitting a $1/f^\alpha$ signal.

By scanning through α , systems of wide interest may be generated. For example, $\alpha=0, 1, 2, 4$ correspond respectively to white noise, $1/f$ noise [29], an Edwards-Wilkinson interface [30] or Brownian curve, and a Mullins-Herring interface [31,32] or random acceleration process [33].

An important feature of $1/f^\alpha$ signals is that correlations may be tuned by the parameter α . Indeed, as one can see in Fig. 1, an α scan leads us from the absence of correlations ($\alpha=0$, white noise) to the limit of a deterministic signal ($\alpha = \infty$). In between $\alpha=0$ and $\alpha \rightarrow \infty$, $\alpha_c=1$ separates decaying

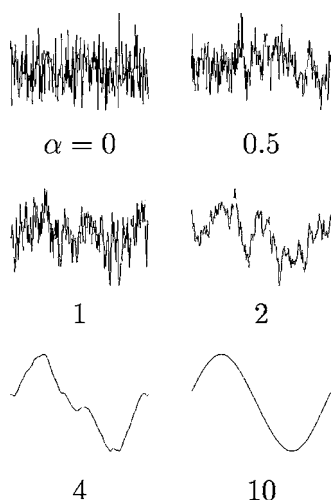


FIG. 1. Typical profiles of various $1/f^\alpha$ signals of length $N = T/\tau = 8192$. Note that, contrary to the visual illusion, the $0 \leq \alpha < 1$ surfaces are flat, while the $1 \leq \alpha < \infty$ signals are rough. In the former case, the amplitude of the signals is size independent, while in the latter case the amplitude diverges with system size. For ease of comparison, we have rescaled the signals to be approximately equal in height.

($0 \leq \alpha < 1$) and strongly correlated ($1 \leq \alpha < \infty$) signals. As we shall see, the extreme statistics is different in these two regions, thus it may be worth spelling out the distinctions between decaying and strong correlations. We therefore briefly describe some known results regarding the correlations in $1/f^\alpha$ signals that will be relevant to the understanding of the rest of the paper.

A global (integral) characteristic of correlations is given by the mean-square fluctuations of the signal, called roughness or width in surface terminology [34,35]

$$w_2 = \overline{[h(t) - \bar{h}]^2} = 2 \sum_{n=1}^{N/2} |c_n|^2, \quad (7)$$

where the overbar indicates an average over t , and the second equality shows that w_2 is the integrated power spectrum of the system. This quantity has been much investigated [28,36] and its probability distribution will be compared to the extreme statistics of the surface in Sec. XI. For the present purpose it is sufficient to recall that the ensemble average over surfaces, $\langle w_2 \rangle$, yields the following asymptote for large system sizes ($T \rightarrow \infty$):

$$\langle w_2 \rangle \sim \begin{cases} T^{\alpha-1} & \text{for } 1 < \alpha \leq \infty, \\ \ln T/\tau & \text{for } \alpha = 1, \\ \tau^{\alpha-1} & \text{for } 0 \leq \alpha < 1. \end{cases} \quad (8)$$

Thus the fluctuations diverge with system size for $1 \leq \alpha < \infty$ in contrast to the finite fluctuations in the $0 \leq \alpha < 1$ regime. Since diverging fluctuations are the sign of strong correlations, this gives a reason for separating the $0 \leq \alpha < 1$ and $1 \leq \alpha < \infty$ regions and attaching the name of decaying and strong correlations to each, respectively.

A more detailed characterization of the α dependence of the correlation can be obtained by examining the correlation function $C_\alpha(t, T) = \langle h(t')h(t'+t) \rangle$ itself. A simple calculation shows that the limit $T \rightarrow \infty$ and $t/T \rightarrow \text{finite}$ yields the following scaling form:

$$C_\alpha(t, T) = T^{\alpha-1} F_\alpha(t/T), \quad (9)$$

and that the nature of the correlations follows from the properties of scaling function F_α .

For $1 < \alpha < \infty$, the scaling function is of order $O(1)$ and $F_\alpha(t/T \rightarrow 0)$ is finite. As a consequence,

$$C_{\alpha>1}(t, T) \sim T^{\alpha-1}, \quad (10)$$

so that the correlations diverge in the $T \rightarrow \infty$ limit. The divergence is also present for $\alpha=1$ but it is only logarithmic, $C_1(t, T) \sim \ln(T/\tau)$. Systems with $1 \leq \alpha < \infty$ can therefore be regarded as *strongly correlated*.

For $0 < \alpha < 1$, the correlations are $O(1)$ since the scaling function behaves as $F_\alpha(u) \sim u^{1-\alpha}$ for $u \ll 1$ and, consequently, one has a power law decay of correlations, independent of system size

$$C_{\alpha<1}(t, T) \sim 1/t^{1-\alpha}. \quad (11)$$

In the bulk ($u \sim 1/2$), the correlations quickly approach zero, $C_\alpha \sim 1/T^{1-\alpha}$ in the $T \rightarrow \infty$ limit. The correlations disappear entirely for $\alpha=0$ since, in this case, $h(t)$ are i.i.d. variables. Systems with $0 \leq \alpha < 1$ have *decaying correlations* hence the name used for their identification.

Thus we see how the regions $0 \leq \alpha < 1$ and $1 \leq \alpha < \infty$ are distinguished. Furthermore, we also have a characterization of correlations taken into account when we study the EVS of periodic Gaussian $1/f^\alpha$ signals.

III. EXTREME STATISTICS: TECHNICALITIES

The quantity of interest is the distribution function $P(h_m)$ of the maximum height h_m of the signal measured from the average, as defined in Eq. (1). In order to construct the histogram for the frequency distribution of h_m , we generate a large number ($\approx 10^6 - 10^7$) of signals, as prescribed by the action $S[c_k; \alpha]$ in Eq. (3) [37]. Each signal is Fourier transformed and the real-space signal, which has zero average ($c_0=0$), is used to determine the value of h_m . Finally, the h_m 's are binned to build the histogram for the MRH distribution.

Since h_m is selected as the largest from $N = T/\tau$ numbers, $P(h_m)$ obtained by the above recipe depends on N . The goal of EVS is to find the limiting distribution which emerges for $N \rightarrow \infty$

$$P(z) = \lim_{N \rightarrow \infty} a_N P_N(h_m = a_N z + b_N). \quad (12)$$

Here a_N and b_N are introduced to take care of the possible singularities in $\langle h_m \rangle_N$ and in $\sigma_N^2 = \langle (h_m - \langle h_m \rangle)^2 \rangle$ (one expects, e.g., that $\langle h_m \rangle_{N \rightarrow \infty} \rightarrow \infty$ for distributions with no finite upper end point).

For any finite N , the parameters a_N and b_N can be related to $\langle h_m \rangle_N$ and σ_N and, in practice, one builds a scaled distribution function where a_N and b_N do not play any role. In the

following, we shall employ two distinct scaling procedures. If the large N behaviors of $\langle h_m \rangle_N$ and σ_N coincide (e.g., $\langle h_m \rangle_N \sim \sigma_N \sim N^\theta$) then we use *scaling by the average* by introducing the variable

$$x = h_m / \langle h_m \rangle_N \quad (13)$$

which ensures that $\langle x \rangle = 1$ and makes the corresponding scaling function

$$\Phi(x) = \lim_{N \rightarrow \infty} \Phi_N(x) = \lim_{N \rightarrow \infty} \langle h_m \rangle_N P_N(\langle h_m \rangle_N x) \quad (14)$$

devoid of any fitting parameters.

If $\langle h_m \rangle_N$ and σ_N scale differently in the large N limit then the above procedure leads either to a delta function or to an ever widening distribution. One can deal with this problem by measuring h_m from $\langle h_m \rangle$ in units of the standard deviation, i.e., by introducing the scaling variable

$$y = \frac{h_m - \langle h_m \rangle}{\sqrt{\langle h_m^2 \rangle - \langle h_m \rangle^2}} = (h_m - \langle h_m \rangle) / \sigma_N. \quad (15)$$

Using y will be called *σ scaling* and the corresponding scaling function will be denoted by $\tilde{\Phi}(y)$. Provided the limit $N \rightarrow \infty$ exists,

$$\tilde{\Phi}(y) = \lim_{N \rightarrow \infty} \tilde{\Phi}_N(y) = \lim_{N \rightarrow \infty} \sigma_N P_N(\langle h_m \rangle_N + \sigma_N y) \quad (16)$$

is again a function without any fitting parameters.

IV. EVS IN THE REGIME OF DECAYING CORRELATIONS ($0 \leq \alpha < 1$)

In the white-noise limit $\alpha \rightarrow 0$, each point on the signal constitutes a random i.i.d. variable with Gaussian distribution. Under these conditions, the MRH limiting distribution falls under the domain of attraction of the Fisher-Tippett-Gumbel distribution [1,2]. In fact, in the range $0 \leq \alpha < 1$, it has been shown that the decaying correlations are too weak to change the FTG limit [27]. Therefore, in the regime of decaying correlations, the MRH statistics of $1/f^\alpha$ signals may be said to be universal.

However, in the case of i.i.d. random variables drawn from a Gaussian parent distribution (i.e., for $\alpha=0$), it has also been established that the convergence in N towards the limiting FTG distribution is logarithmically slow [1,38,39]. Therefore, in practice, the MRH distribution may appear different from FTG. An even worse rate of convergence may be expected with increasing α , since, heuristically, increasing correlations decrease the effective number of degrees of freedom. In Fig. 2 we illustrate this trend by comparing numerical MRH distributions for a range of α but fixed N with the FTG limiting distribution. For $\alpha < 0.5$ the numerical distributions are practically indistinguishable from the case $\alpha=0.5$. This figure serves as a warning when comparing real-world data with known extreme value distributions.

We note here that Eichner *et al.* [40] have recently investigated EVS for $\alpha=0.6$. Although they do not spell it out explicitly, their Figs. 2 and 3 do demonstrate that the conver-

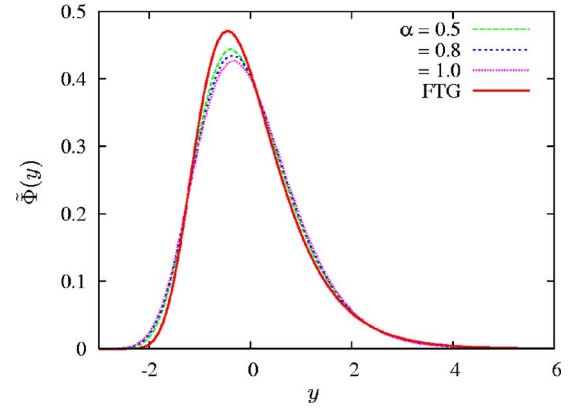


FIG. 2. (Color online) Numerically constructed MRH distributions for $\alpha=0.5, 0.8$, and 1.0 for system size $N=T/\tau=16384$. The FTG distribution is shown by the thick black line. Each distribution is rescaled to zero mean and unit standard deviation. It should be mentioned that the $\alpha < 0.5$ curves are not displayed since they are indistinguishable from the $\alpha=0.5$ case.

gence at $\alpha=0.6$ (Fig. 3) is slower than at $\alpha=0$ (Fig. 2), in agreement with our findings described above.

In order to shed more light on convergence rates towards limiting distributions, we have measured the skewness $\gamma_1 = \kappa_3 / \kappa_2^{3/2}$ where κ_n is the n th cumulant of the MRH distribution function. The results for a range of α and N are displayed in Fig. 3. From this plot one can discern a number of remarkable features. First, in the range $0 \leq \alpha < 1$, we note that the measured skewnesses are far from the skewness of the FTG distribution (approximately 1.140...), even for the largest system size available. Second, for $\alpha=0$, we know theoretically that the convergence rate is logarithmically slow, but, somewhat surprisingly, this convergence rate appears to be shared for all $\alpha \leq 0.5$, after which convergence slows down markedly. Thus the universality in the ultimate limiting distribution for $0 \leq \alpha < 1$ may not carry over to a universality in the finite-size corrections. Note that if we did

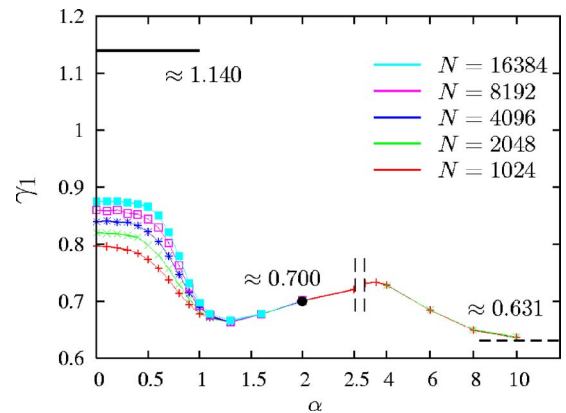


FIG. 3. (Color online) Strong finite-size effects at low values of α as seen in the scaled skewness, $\gamma_1 = \kappa_3 / \kappa_2^{3/2}$ of the MRH distribution. Note the exponential increasing system sizes $N=T/\tau$ used for comparisons. Note also that the scale of the horizontal axis changes at $\alpha=2.5$. The limiting value of γ_1 for $\alpha < 1$ is $\gamma_1 \approx 1.140$. Other exactly known values are $\gamma_1(\alpha=2) \approx 0.700$ and $\gamma_1(\alpha \rightarrow \infty) \approx 0.631$.

not know the limit but would try to determine it from finite- N skewnesses, then for $\alpha \leq 1$ we would be wrong to conclude that the asymptotic value had nearly been reached.

The case of strong correlations is discussed in the following sections. Here, we just observe that the skewnesses for $\alpha > 1$ rapidly collapse for different N , and that they are virtually indistinguishable from each other for $\alpha \geq 1.5$. In this case we may be quite sure that the skewnesses have practically reached their limiting values, since they match their corresponding theoretical values for $\alpha=2$ and ∞ with high accuracy. As we shall argue in Sec. VIII, in contrast to the very slow convergence for $0 \leq \alpha < 1$, convergence rate improves as it becomes a power law for $\alpha > 1$.

V. STRONG-CORRELATION REGIME: EXACT RESULTS FOR $\alpha=2$ AND $\alpha=\infty$

The $1 \leq \alpha < \infty$ region is characterized by diverging mean-square fluctuations [see Eq. (8)]. Since $\langle h_m \rangle \geq \sqrt{\langle w_2 \rangle}$, this is also a range where the characteristic scale of $\langle h_m \rangle$ diverges with the size of the system at least as $\langle h_m \rangle \sim T^{(\alpha-1)/2}$. An important exact result in the strongly correlated regime is related to the Brownian random walk ($\alpha=2$). Majumdar and Comtet [7,8] have shown that $\langle h_m \rangle \sim \sqrt{T}$ and, furthermore, they calculated the MRH distribution using path-integral techniques as well as by making a mapping to the problem of the area distribution under a Brownian excursion [41,42]. The resulting distribution is known as the Airy distribution. Under *scaling by the average* ($x = h_m / \langle h_m \rangle$), the Airy distribution can be written as follows (note that slightly different scaling has been used in [7,8]):

$$\Phi(x) = \frac{8\sqrt{3}}{\sqrt{\pi x^{10/3}}} \sum_{n=1}^{\infty} e^{-v_n x^2} v_n^{2/3} U(-5/6, 4/3, v_n x^2). \quad (17)$$

Here $U(a, b, z)$ is the confluent hypergeometric function and $v_n = (2/\pi)(2\alpha_n/3)^3$ is related to the n th zero $-\alpha_n$ of the Airy function.

The small and large x asymptotes of $\Phi(x)$ have also been calculated [7,8] with the results

$$\Phi(x \rightarrow 0) \sim \frac{8\sqrt{3}v_1^{3/2}}{\sqrt{\pi x^5}} e^{-v_1/x^2} \quad (18)$$

and

$$\ln \Phi(x \rightarrow \infty) \sim -3\pi x^2/4. \quad (19)$$

It is noteworthy that the above asymptotes are quite close in functional form to those obtained for the width distribution of the Edwards-Wilkinson model [36].

The plot of $\Phi(x)$ is shown on Fig. 4(a) where a rather fast convergence to the limiting function can be seen (the convergence rate is $T^{-1/2}$ as calculated in [43]). It is remarkable that the convergence is even faster if σ scaling is used [Fig. 4(b)]. The reason for this is the finite-size scaling of higher cumulants of the MRH distribution function. At this point we present this just as a numerical observation. A detailed study

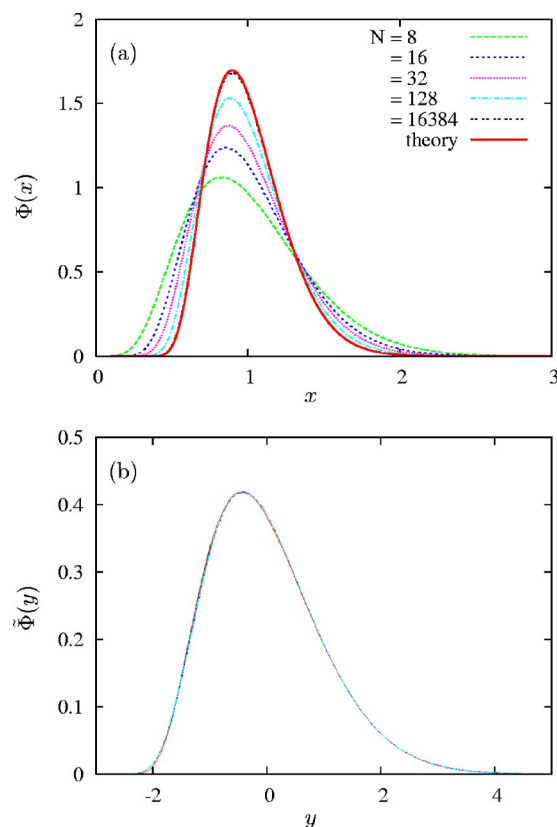


FIG. 4. (Color online) Convergence of the MRH distribution for $\alpha=2$ to its exactly known $N \rightarrow \infty$ limit [7]. Results for same system sizes are displayed in both panels using scaling by the average ($x = h_m / \langle h_m \rangle$) and σ scaling [$y = (h_m - \langle h_m \rangle) / \sigma$] in panels (a) and (b), respectively. Note that, due to the remarkably fast convergence in σ scaling, the curves in panel (b) are practically indistinguishable.

of the finite-size scaling of MRH will be published separately [44].

The review of the properties of the MRH distribution for $\alpha=2$ presented above gives a guidance for the discussion of EVS in the strong correlation regime. As we shall see below, the basic properties of EVS ($\langle h_m \rangle \sim \sqrt{\langle w_2 \rangle}$, the general shape of $\Phi(x)$, the structure of the small- and large- x asymptotics of $\Phi(x)$, and the fast convergence to the limiting function) are similar in the whole $1 < \alpha < \infty$ region.

The other analytically solvable case is the $\alpha \rightarrow \infty$ limit. Indeed, here only the $n=1$ mode survives, and the resulting signal $h(t) = |c_1| \sin(2\pi t/T + \varphi)$. Consequently, $h_m = |c_1|$ and the distribution of h_m is just the distribution of $|c_1|$ given by $P(|c_1|) \sim |c_1| \exp[-(2\pi)^\alpha T^{1-\alpha} |c_1|^2]$. Using the *average scaling*, the scaling function $\Phi_\infty(x) = \langle h_m \rangle P(\langle h_m \rangle x)$ becomes

$$\Phi_\infty(x) = \frac{\pi}{2} x \theta(x) e^{-\pi x^2/4} \quad (20)$$

where $\theta(x)$ is Heaviside's step function. Comparing the above expression with the asymptotes (18) and (19), one can see that, in addition to the disappearance of the small x singularity, the large x asymptote has acquired an extra x factor.

VI. THE PROPAGATOR OF THE GENERALIZED RANDOM ACCELERATION PROCESS: $\alpha=2n$

The derivation of subsequent analytical results on the scale of $\langle h_m \rangle$, and on the small h_m asymptote of the MRH distribution is based on the observation that $1/f^\alpha$ signals are actually paths of generalized random acceleration processes, provided that $\alpha=2n$ is an even integer. This allows a path-integral representation of the MRH distribution function (Sec. VII) from which rather general conclusions can be drawn and, furthermore, as indicated by the simulations, the results can be extended to any $1 < \alpha < \infty$.

The construction of the MRH distribution function in the path integral approach involves the calculation of a normalization factor which, in turn, requires the knowledge of the propagator (also called two-time Green-function, or transition probability) of the random acceleration process. Here we compute this propagator, i.e., the probability density of a position of the stochastic path at some time t conditioned on the initial point.

The equation of motion of the $1/f^{2n}$ trajectory reads

$$h^{[n]}(t) = \frac{d^n h(t)}{dt^n} = \xi(t), \quad (21)$$

where $\xi(t)$ is white noise with zero mean and correlation $\langle \xi(t)\xi(t') \rangle = \delta(t-t')$. Note that $h(t)$ corresponds to the $(n-1)$ st integral of the Brownian random walk trajectory. Equation (21) can be rewritten as a vector Langevin equation

$$\dot{z}_1 = \xi(t), \quad \dot{z}_k = z_{k-1}, \quad (k=2,3,\dots,n), \quad z_n = h. \quad (22)$$

For $n=1$ we have the usual random walk, for $n=2$ the random acceleration problem [33], also extensively studied, while for higher n 's one can speak about the generalized random acceleration processes [45,46]. We are interested in the conditional probability that after time t the trajectory is at $\mathbf{z}=(z_1, z_2, \dots, z_n)$ provided it started from \mathbf{z}^0 . In the following, we denote this propagator by $G_n(\mathbf{z}|\mathbf{z}^0; t)$. Its subscript indicates the dimension of the vector arguments, and it obviously satisfies the recursion relation

$$G_n(\mathbf{z}|\mathbf{z}^0; t) = \int dz_{n+1} G_{n+1}(\mathbf{z}|\mathbf{z}^0; t), \quad (23)$$

where the integration eliminates the dependence on z_{n+1}^0 , too. The propagator has Dirac delta initial condition, $G_n(\mathbf{z}|\mathbf{z}^0; 0) = \delta^{(n)}(\mathbf{z}-\mathbf{z}^0)$, and satisfies the Fokker-Planck equation, obtained in a standard way from the Langevin equation [47],

$$\partial_t G_n = -\hat{H}_n^0 G_n, \quad (24)$$

$$\hat{H}_n^0 = -\frac{1}{2}\partial_1^2 + \sum_{k=1}^{n-1} z_k \partial_{k+1}, \quad (25)$$

where ∂_t and ∂_k are derivatives with respect to t and z_k , respectively. The superscript of \hat{H}_n^0 refers to the fact that we consider here the time evolution (21) without further constraints. The propagator has been calculated in previous studies up to $n=5$ [48,46]. We make an ansatz that matches these functions and we show it to be valid for general n

$$G_n(\mathbf{z}|\mathbf{z}^0; t) = \prod_{k=1}^n \mathcal{G}(\mathbf{a}^k \cdot \mathbf{z} - \mathbf{a}^{0,k} \cdot \mathbf{z}^0; \sigma_k), \quad (26)$$

where $\mathcal{G}(z; \sigma) = \exp(-z^2/2\sigma^2)/\sqrt{2\pi}\sigma$ is a Gaussian PDF with zero mean and variance σ^2 , \mathbf{z}^0 is the initial condition vector, and the vector \mathbf{a}^k only has nonzero components for $i=1, 2, \dots, k$, i.e., for $l > k$ we have $a_l^k = 0$. In order to remove ambiguity we set $a_k^k = 1$. The $\mathbf{a}^k, \mathbf{a}^{0,k}, \sigma_k$ are time dependent quantities to be determined. The above formula amounts to the recursion relation

$$G_n(\mathbf{z}|\mathbf{z}^0; t) = G_{n-1}(\mathbf{z}|\mathbf{z}^0; t) \mathcal{G}(\mathbf{a}^n \cdot \mathbf{z} - \mathbf{a}^{0,n} \cdot \mathbf{z}^0; \sigma_n). \quad (27)$$

Substitution of this ansatz into Eq. (24) leads to equations for the unknown parameters. The solution of the equations as described in Appendix A yields

$$a_k^n = \frac{(-t)^{n-k}(n+k-2)!}{2^{n-1}(2n-3)!!(k-1)!(n-k)!}, \quad (28a)$$

$$a_k^{0,n} = (-1)^{n-k} a_k^n, \quad (28b)$$

$$\sigma_n = \frac{t^{(2n-1)/2}}{2^{n-1}\sqrt{2n-1}(2n-3)!!}. \quad (28c)$$

For illustration, we use the above expressions to calculate and display explicitly the $n=4$ propagator. Noting that the original coordinate, velocity, acceleration, and its time derivative are given by

$$h = z_4, \quad v = z_3, \quad a = z_2, \quad \dot{a} = z_1, \quad (29)$$

respectively, the propagator can be written in the form

$$G_4(\mathbf{z}|\mathbf{z}^0; t) = \frac{720\sqrt{105}}{\pi^2 t^8} e^{-A/2}, \quad (30)$$

where $-A/2$ is the sum of the exponents of the Gaussians in Eq. (26), namely

$$A = \sum_{k=1}^4 A_k, \quad (31)$$

with

$$A_1 = \frac{1}{t}(z_1 - z_1^0)^2, \quad (32a)$$

$$A_2 = \frac{12}{t^3} \left[z_2 - z_2^0 - \frac{t}{2}(z_1 + z_1^0) \right]^2, \quad (32b)$$

$$A_3 = \frac{720}{t^5} \left[z_3 - z_3^0 - \frac{t}{2}(z_2 + z_2^0) + \frac{t^2}{12}(z_1 - z_1^0) \right]^2, \quad (32c)$$

$$A_4 = \frac{100800}{t^7} \left[z_4 - z_4^0 - \frac{t}{2}(z_3 + z_3^0) + \frac{t^2}{10}(z_2 - z_2^0) - \frac{t^3}{120}(z_1 + z_1^0) \right]^2. \quad (32d)$$

Up to the $k=3$ term this incorporates the propagators of the random walk, $k=1$, random acceleration, $k\leq 2$, and random velocity of acceleration, $k\leq 3$, and the above expressions are in agreement with previous results [46]. Note that, independently of k , we have $a_k^k = a_k^{0,k} = 1$, and

$$a_{k-1}^k = -a_{k-1}^{0,k} = t/2, \quad (33)$$

but for $l\leq k-2$ the a_l^k 's will vary with both l and k .

Later, for the construction of the formula for the MRH distribution, we will need a special property of the propagator. Namely, if we consider the propagator of a periodic path of length T and integrate it over the common values of the velocity, acceleration, etc., at the end points, we get the surprisingly simple result

$$\int \prod_{k=1}^{n-1} dz_k^0 G_n(z^0|z^0; T) = T^{-(n-1/2)} (2\pi)^{-1/2}. \quad (34)$$

Indeed, the periodic propagator does not depend on z_n^0 ; the integration over z_{n-1}^0 cancels the normalizing constant of the n th Gaussian but brings in a factor of $1/T$. The integration over z_{n-2}^0 does the same with the $(n-1)$ st Gaussian, and so on, until finally we are left with the norm factor of the $n=1$ Gaussian, $1/\sqrt{2\pi T}$, divided by T^{n-1} , as shown in Eq. (34). The key to this remarkable cancellation of the total numeric prefactor of the propagator is that Eq. (33) holds uniformly for all k 's.

VII. PATH INTEGRAL FORMALISM AND THE TRACE FORMULA FOR THE MRH ($\alpha=2n$)

For $\alpha=2$ Majumdar and Comtet [7,8] introduced a path integral representation of the MRH distribution. The technique allowed for the formulation of the PDF in terms of the spectrum of a quantum mechanical, one-dimensional, Hamiltonian \hat{H} with a hard wall and elsewhere linear potential, through the trace of $e^{-\hat{H}T}$, valid in the case of periodic boundary conditions. The spectrum is known to consist of the Airy zeros, so the trace formula resulted in the PDF called the Airy distribution.

In what follows we show that, in the case of periodic boundary conditions, for a general $\alpha=2n$, $n=2,3,\dots$ an analogous trace formula holds. Remarkably, the formula turns out to be essentially the same as in the $\alpha=2$ case, with the only difference that now a generalized ‘‘Hamiltonian’’ \hat{H}_n appears. However, the \hat{H}_n , a differential operator in an n dimensional space, is no longer Hermitian. Whereas we shall not solve the spectral problem necessary for the calculation of the MRH distribution, this formulation will allow us to (i) determine the scale of the MRH as function of T and (ii) give explicitly the initial asymptote of the PDF, with the only undetermined parameter being the ground state energy of the Hamiltonian \hat{H}_n . What is more, the results (i) and (ii) will lend themselves to a continuation to real α 's, so the use of the path integral technique extends beyond its original region of validity, the generalized random acceleration problem $\alpha=2n$.

We begin with the probability functional of a periodic path $h(t)$, where h is measured from the time average,

$$\mathcal{P}[h(t)] = \mathcal{A} \exp\left(-\frac{1}{2} \int_0^T dt [h^{[n]}(t)]^2\right) \delta\left(\int_0^T dt h(t)\right). \quad (35)$$

Following [7,8] we have introduced a normalizing coefficient \mathcal{A} , ensuring

$$\int_{\text{PBC}} \mathcal{D}_n h(t) \mathcal{P}[h(t)] = 1, \quad (36)$$

where PBC indicates that periodic boundary conditions for all derivatives of the path up to $h^{[n-1]}$ is understood. The measure $\mathcal{D}_n h(t)$ is defined such that the propagator $G_n(z|z^0; T)$ of Sec. VI is a path integral without extra normalization, and the boundary conditions of the integral are specified by the arguments of G_n , i.e.,

$$G_n(z|z^0; T) = \int \mathcal{D}_n h(t) \exp\left(-\frac{1}{2} \int_0^T dt [h^{[n]}(t)]^2\right), \quad (37)$$

with $h^{[n-k]}(0) = z_k^0$, $h^{[n-k]}(T) = z_k$, where $k=1, \dots, n$. This $\mathcal{D}_n h(t)$ is in fact the measure leading naturally to the quantum-mechanical-like operator representation of the path integral

$$G_n(z|z^0; T) = \langle z | e^{-\hat{H}_n T} | z^0 \rangle, \quad (38)$$

where \hat{H}_n^0 is given by Eq. (25), and $|z^0\rangle\langle z|$ are the right (left) eigenvectors corresponding to the n -dimensional positions indicated therein. Note that, since this Hamiltonian is non-Hermitian for $n\geq 2$, the left and right eigenfunctions are different in general.

A third representation of the propagator we shall utilize comes from a path integral by a measure of one order lower as

$$G_{n+1}(z|z^0; T) = \int \mathcal{D}_n h(t) \exp\left(-\frac{1}{2} \int_0^T dt [h^{[n]}(t)]^2\right) \times \delta\left(z_{n+1} - \int_0^T h(t) dt - z_{n+1}^0\right). \quad (39)$$

Here the Dirac delta produces the normalized density for the added area variable z_{n+1} . Note that if we take into account Eq. (37) then the consistency relation (23) immediately follows.

In order to determine the normalization coefficient \mathcal{A} in Eq. (35), we express the equal-points propagator complemented with the area variable set to zero at both ends. By integrating over the path except for a single point and using Eqs. (35) and (39)

$$P_{\text{PBC}:z^0}(z^0) = \int_{\text{PBC}:z^0} \mathcal{D}_n h(t) \mathcal{P}[h(t)] = \mathcal{A} G_{n+1}(z^0, 0 | z^0, 0; T), \quad (40)$$

where the mark PBC: z^0 refers to the time derivatives at the ends fixed at $h^{[k]}(0) = h^{[k]}(T) = z_{n-k}^0$, $k=0, \dots, n-1$. The

$P_{\text{PBC}}(z^0)$ is the joint probability density of $h^{[k]}(t)=z_{n-k}^0$'s in a periodic path at any fixed time t , so as a by-product we obtained that density in terms of the propagator, explicitly given in Sec. VI. That joint probability density is obviously normalized to unity. However, we know from Eq. (34) that the integral of the right-hand side is independent of the z_{n+1}^0 st variable, and therefore we have

$$\mathcal{A} = T^{n+1/2} \sqrt{2\pi}. \quad (41)$$

For $n=1$ the normalizing coefficient derived in [7,8] is recovered.

The integrated distribution $M(h_m; T)$ of the MRH, i.e., the probability that the maximum does not exceed h_m , has been formulated in terms of a path integral in [7,8]. That expression is valid for any path density $\mathcal{P}[h(t)]$ and reads formally as

$$\begin{aligned} M(h_m; T) &= \int_{-\infty}^{h_m} dh P(h; T) \\ &= \int_{\text{PBC}} \mathcal{D}h(t) \mathcal{P}[h(t)] \prod_t \theta(h_m - h(t)). \end{aligned} \quad (42)$$

Note that here $P(h_m; T)$ is the density of MRH. Changing the integration variable and then introducing the hard wall potential $V_0(h)=\infty$ for $h < 0$ and $V_0(h)=0$ for $h > 0$, one obtains

$$\begin{aligned} M(h_m; T) &= \int_{\text{PBC}} \mathcal{D}h(t) \mathcal{P}[h_m - h(t)] \prod_t \theta(h(t)) \\ &= \int_{\text{PBC}} \mathcal{D}h(t) \mathcal{P}[h_m - h(t)] e^{-\int_0^T dt V_0(h(t))}. \end{aligned} \quad (43)$$

Using the specific form (35) of the probability functional we find

$$\begin{aligned} M(h_m; T) &= \mathcal{A} \int_{\text{PBC}} \mathcal{D}h(t) \delta\left(h_m T - \int_0^T dt h(t)\right) \\ &\quad \times \exp\left[-\int_0^T dt \left\{ \frac{1}{2} (h^{[n]})^2 + V_0(h(t)) \right\}\right]. \end{aligned} \quad (44)$$

Next, we introduce the scaled Laplace transform of the integrated MRH distribution

$$\begin{aligned} K(u; T) &= T \int_0^\infty dh_m e^{-uh_m T} M(h_m; T) \\ &= \mathcal{A} \int_{\text{PBC}} \mathcal{D}h(t) \exp\left[-\int_0^T dt \left\{ \frac{1}{2} (h^{[n]})^2 + uV(h(t)) \right\}\right], \end{aligned} \quad (45)$$

where the potential $V(h)=\infty$ for $h < 0$ and $V(h)=h$ for $h > 0$.

In order to find $K(u; T)$, we write down the evolution equation for the PDF of the position and its derivatives $P_n(z; t)$ corresponding to the above path probability,

$$\partial_t P_n = -\hat{H}_n(u) P_n, \quad (46)$$

$$\hat{H}_n(u) = \hat{H}_n^0 + uV(z_n), \quad (47)$$

where \hat{H}_n^0 was given in Eq. (25) and the variables z_k are defined by Eq. (22). Thus the Laplace transform can be written in short as

$$K(u; T) = \mathcal{A} \text{Tr} \exp(-\hat{H}_n(u)T). \quad (48)$$

It is straightforward to show that the eigenvalues $E_{n,\omega}(u)$ of $\hat{H}_n(u)$, where ω summarizes all discrete indices, obey a simple scaling in u . For that purpose, let us consider the eigenvalue problem for $h=z_n > 0$

$$\hat{H}_n(u)\psi = \left[-\frac{1}{2}\partial_1^2 + \sum_{k=1}^{n-1} z_k \partial_{k+1} + uz_n \right] \psi = E_{n,\omega}(u)\psi \quad (49)$$

and apply a scale transformation by substituting

$$u^{\beta_k} z_k \rightarrow z_k, \quad u^\delta E_n \rightarrow E_n. \quad (50)$$

We recover an equation free of u , if all powers multiplying various terms are the same, that is

$$-2\beta_1 = \beta_1 - \beta_2 = \dots = \beta_{n-1} - \beta_n = \beta_n + 1 = \delta, \quad (51)$$

so $\beta_k = (n-k+1)\delta - 1$ and also $-2\beta_1 = \delta$. Hence $\delta = 2/(2n+1)$, so the eigenvalues scale like $E_{n,\omega}(u) = \epsilon_{n,\omega} u^{2/(2n+1)}$, where $\epsilon_{n,\omega}$ is the spectrum of $\hat{H}_n = \hat{H}_n(1)$.

It thus follows that, using Eq. (41), we get the scaling relation for the Laplace transform of the integrated distribution

$$K(u; T) = T^{n+1/2} \mathbf{K}(uT^{n+1/2}), \quad (52)$$

$$\begin{aligned} \mathbf{K}(s) &= \sqrt{2\pi} \text{Tr} \exp(-\hat{H}_n s^{2/(2n+1)}) \\ &= \sqrt{2\pi} \sum_\omega \exp(-\epsilon_{n,\omega} s^{2/(2n+1)}). \end{aligned} \quad (53)$$

Hence, using Eq. (45), we obtain for the PDF of the MRH $P(h_m; T)$ and its moment generating function $G(u; T)$ in scaling forms

$$P(h_m; T) = \partial_{h_m} M(h_m; T) = T^{1/2-n} P(h_m T^{1/2-n}), \quad (54)$$

$$G(v; T) = \int_0^\infty dh_m P(h_m; T) e^{-vh_m} = G(vT^{n-1/2}), \quad (55)$$

where

$$\begin{aligned} G(s) &= \int_0^\infty dz P(z) e^{-sz} = s\mathbf{K}(s) = \sqrt{2\pi} s \text{Tr} \exp(-\hat{H}_n s^{2/(2n+1)}) \\ &= \sqrt{2\pi} s \sum_\omega \exp(-\epsilon_{n,\omega} s^{2/(2n+1)}). \end{aligned} \quad (56)$$

Note that the same symbols \mathbf{K}, P, G are used for single- and double-argument functions, but that should not cause confusion. Remarkably, the trace formula is exactly the same as in

the case of the simple random walk $n=1$, with the Hamiltonian \hat{H}_1 replaced by \hat{H}_n . Note that, in the special case of $n=1$, the scaling function of the MRH distribution (17) is ultimately recovered from the above trace formula [8].

The scaled moment generating function Eq. (56) together with the preceding scaling formulas are our main result here. In the next two sections, we shall exploit the above results to draw conclusions about the scale and the small argument asymptote of the MRH distribution function.

VIII. STRONG-CORRELATION REGIME ($1 < \alpha < \infty$)

In order to evaluate the trace formula one would need the energy eigenvalues of $\hat{H}_n(1)$. Although they are known [7] only for $n=1$, assuming that these eigenvalues exist, the scale of the MRH in T can be derived since Eq. (54) yields

$$\langle h_m \rangle \sim T^{n-1/2}. \quad (57)$$

As one can see, the scale of $\langle h_m \rangle$ is the same as that of the square root of the roughness [28], i.e., we have $\langle h_m \rangle \sim \sqrt{\langle w_2 \rangle}$ just as in the case of random walks [7]. It should be emphasized that while the above reasoning holds strictly for $\alpha=2n$, the exponent can, in fact, be continued naturally to real values. Thus it is plausible to surmise that $T^{(\alpha-1)/2}$ is the scale of the MRH for any $\alpha > 1$. This power emerges quite sharply for $\alpha=1.3, 1.6, 2, 4$ in numerical simulations as shown on the first panel of Fig. 5.

Figure 5 also displays the second and third cumulants of $P(h_m, T)$. We can observe the emergence of well defined scaling with T

$$\kappa_k(\alpha) \sim T^{k(\alpha-1)/2}. \quad (58)$$

The scaling exponents are again equal to those of the cumulants of the width distribution provided the $h_m \sim \sqrt{w_2}$ correspondence is used. This suggests that there is an intimate connection between the fluctuations of MRH and those of the signal width.

In order to see how the general shape changes as α is increased, we have performed simulations as described in Sec. III. The results are shown in Fig. 6 where we used *scaling by the average* to present the scaling functions $\Phi_\alpha(x)$.

The main features can be readily seen. The scaling function is a unimodal (single peaked) function which spreads out as α increases and approaches its $\alpha \rightarrow \infty$ limit [see Eq. (20)] rather fast. This is not entirely surprising since a glance at Fig. 1 convinces one that the $\alpha=10$ signal already consists of a single mode for all practical purposes, and thus the MRH distribution will be very well approximated by the $\Phi_\infty(x)$ function.

The function decays to zero extremely fast in the $x \rightarrow 0$ limit. The nonanalytical behavior and the actual functional form at small x will be the subject of the next section. Here, we call the reader's attention to the fact that the region where the nonanalytic asymptotic behavior dominates is shrinking as α increases and, according to Eq. (20), entirely disappears in the $\alpha \rightarrow \infty$ limit.

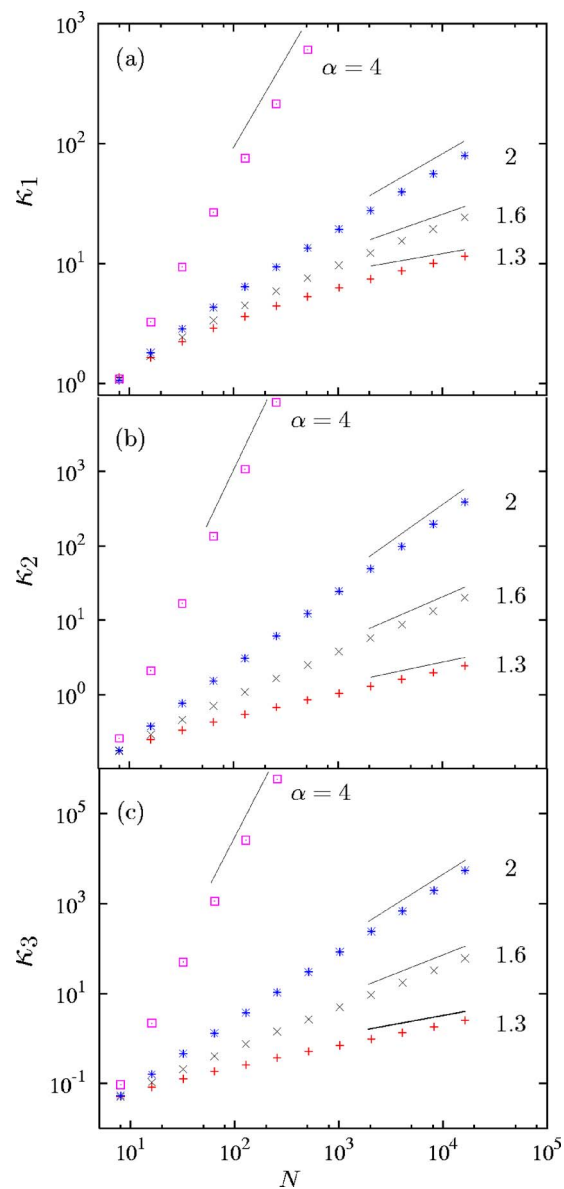


FIG. 5. (Color online) Cumulants, κ_k , of the MRH distribution for various $\alpha > 1$ showing that $\kappa_k(\alpha)$ scales with system size, $N = T/\tau$, as $\kappa_k(\alpha) \sim N^{k(\alpha-1)/2}$. The straight lines have the appropriate asymptotic slopes $k(\alpha-1)/2$.

The large x limit is harder to treat analytically and we have only numerical evidence (Fig. 7) that the asymptotic behavior for large x is given by

$$\Phi(x) \sim Cx^\gamma e^{-Bx^2}, \quad (59)$$

where the parameters B , C , and γ depend on α . The above functional form is consistent with the exact result at $\alpha = \infty$ [see Eq. (20)]. At $\alpha=2$, the ansatz of a Gaussian decay was shown to be in agreement [7] with the large-order moments of the distribution function. However, the possibility of a prefactor x^γ was not excluded by the analysis. We found that the generalized asymptote (59) with $\gamma \approx 2$ gives a superior fit to the large- x ($x > 1.5$) behavior of the exactly known PDF.

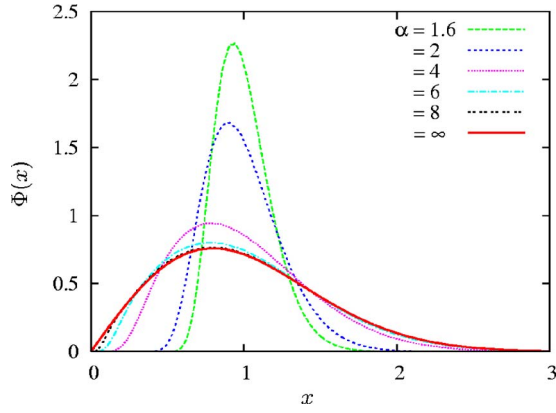


FIG. 6. (Color online) Numerically constructed MRH distributions for various $1 < \alpha < \infty$. The $\alpha = \infty$ curve is the analytic result given in Eq. (20). System sizes $N \leq 16384$ were sufficiently large to observe the convergence of the PDFs within the width of the lines drawn. Note that the $\alpha = 8$ results are almost indistinguishable from the $\alpha \rightarrow \infty$ limit.

We have also fitted our numerical data in the region $x > 1.5$ for larger α 's, resulting in $\gamma \approx 1.4$ and $\gamma \approx 1.1$ for $\alpha = 3$ and 4, respectively. The general trend of the exponent γ with increasing α is consistent with the $\alpha \rightarrow \infty$ limit of $\gamma_\infty = 1$.

IX. INITIAL ASYMPTOTE

The trace formula (56) allows us to perform an asymptotic analysis of the MRH distribution for small arguments. The calculation is based on the large s behavior of the moment generating function (56), wherein we assume that there is a positive, $\alpha = 2n$ -dependent, nondegenerate ground state energy $\epsilon_0(\alpha)$, which gives the leading term of the sum (while α is strictly even, several results will lend themselves to continuation). Under this assumption, the PDF in the scaled variable $z = h_m T^{(1-\alpha)/2}$ is asymptotically given by

$$P(z) = \int \frac{ds}{2\pi i} G(s) e^{sz} \approx \int \frac{ds}{2\pi i} s \sqrt{2\pi} \exp(sz - \epsilon_0 s^{2/(\alpha+1)}). \quad (60)$$

The above integral can be calculated using the saddle point method. For small z , the saddle point of the exponent is located on the real axis at

$$s^* \approx \left(\frac{2\epsilon_0}{(\alpha+1)z} \right)^{(\alpha+1)/(\alpha-1)} \quad (61)$$

and the integral in the neighborhood of the saddle point reduces to evaluating a Gaussian integral which yields the following asymptote:

$$P(z) \approx C z^{-\gamma} \exp(-B/z^\beta), \quad (62)$$

where the parameters are given by

$$\beta = \frac{2}{\alpha-1}, \quad (63a)$$

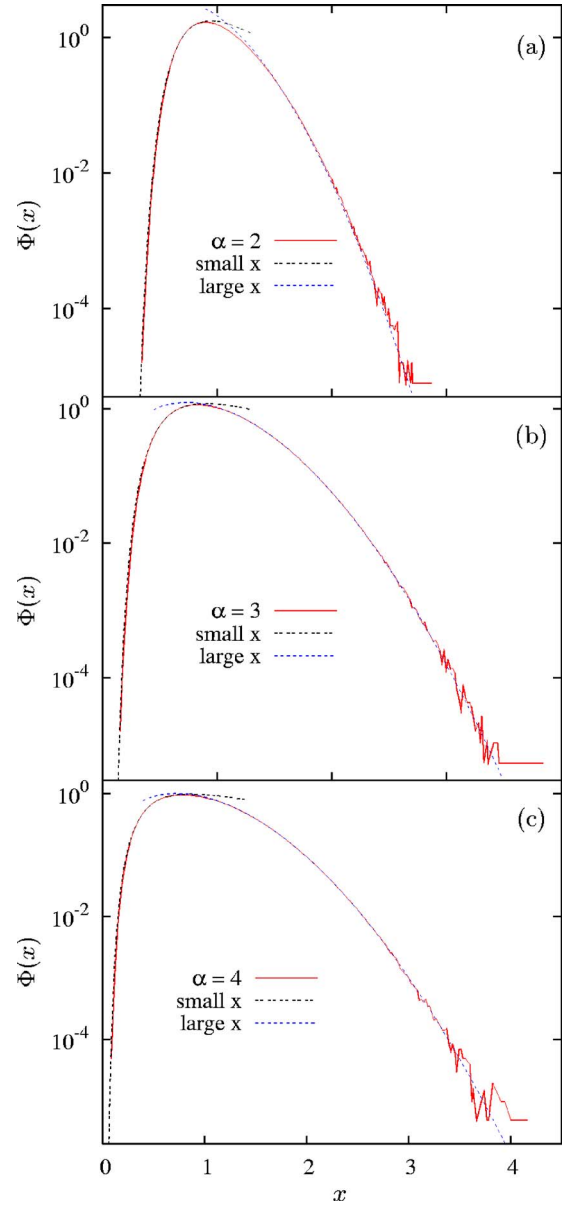


FIG. 7. (Color online) MRH distributions for (a) $\alpha = 2$ (b) $\alpha = 3$, and (c) $\alpha = 4$, calculated for system size $N = 16384$ (solid lines). The small and large x asymptotes (dashed lines) are also shown. The small x behavior in the range $0 < x < 1$ is fitted to the functional form (62) with the exponents β, γ taken from Eq. (63). The prefactors B, C are fitting parameters [note that the formulas in Eq. (63) contain an unknown parameter ϵ_0]. Large x data in the range $x > 1.5$ are fitted to the form (59), where B, C , and γ are fitting parameters.

$$\gamma = \frac{2\alpha+1}{\alpha-1}, \quad (63b)$$

$$B = \frac{\alpha-1}{2} \left(\frac{2\epsilon_0}{\alpha+1} \right)^{(\alpha+1)/(\alpha-1)} \quad (63c)$$

$$C = \sqrt{\frac{\alpha+1}{\alpha-1}} \left(\frac{2\epsilon_0}{\alpha+1} \right)^{(3/2)(\alpha+1)/(\alpha-1)}. \quad (63d)$$

One should note that the exponents β and γ depend only on α while the amplitudes also depend on the ground state energy, $\epsilon_0(\alpha)$. The value of $\epsilon_0(\alpha)$ is known only for $\alpha=2$ where $\epsilon_0(2)=\alpha_1/\sqrt[3]{2}$, with $\alpha_1=2.3381$ being the absolute value of the first zero of the Airy function [7,8].

It should be emphasized that we did not scale the mean to 1, being ignorant about the full PDF as well as its mean for general α . So if comparing the above formula to the numerically scaled PDF as function of $x=z/\langle z \rangle$ then the factors B, C will change and become fitting parameters. Figure 7 demonstrates the fit of Eq. (62) to simulation results for several α 's, and we find that the fits are excellent in a surprisingly large interval. It should be noted that in the large α limit the initial slope is positive, so one expects a decreasing range of validity of the asymptote for increasing α , nevertheless, the fit on Fig. 7 is quite good even for the largest α . The case $\alpha=3$ demonstrates the continuation of the $\alpha=2n$ based formula, and suggests that naive continuation of at least the exponents β, γ in Eq. (63) is justified.

Returning to the problem of scale dependence of the amplitudes B and C , we note that even if the full PDF is unknown, one can construct a parameter from the small- x asymptote which does not depend on the scale. In order to see this, let us consider scaling by the average. With the rescaled variable x , one has the PDF as $\langle z \rangle P(x \langle z \rangle)$ and writing it again in the form (62) yields the following change of the amplitudes:

$$B' = \frac{B}{\langle z \rangle^\beta}, \quad C' = \frac{C}{\langle z \rangle^{\gamma-1}}. \quad (64)$$

It follows from the above expressions that the combination

$$D = \frac{B^{(\alpha+2)/2}}{C} = \frac{B'^{(\alpha+2)/2}}{C'} \\ = \frac{(\alpha-1)^{(\alpha+3)/2}}{2^{(\alpha+2)/2} \sqrt{\alpha+1}} \left(\frac{2\epsilon_0}{\alpha+1} \right)^{(\alpha+1)/2} \quad (65)$$

remains independent of any scale change.

We should reiterate that the energy parameter $\epsilon_0(\alpha)$ is not known generally, but it is plausible to assume that it is a well defined number. It may be determined numerically for $\alpha=2n$ by a direct study of the corresponding local Hamiltonian. Remarkably, however, the above asymptotic formula allows for the computation of $\epsilon_0(\alpha)$ for any $\alpha>1$ from a numerical fit of the simulation result. Thus, precise MRH statistics effectively extract the ground state energy level of the Hamiltonian without solving the corresponding differential equation. Continuation of Eq. (62) for $\alpha \neq 2n$ is also natural here, but in this case we have a nonlocal Hamiltonian, whose spectral problem would be an even more challenging task to solve. Unfortunately, very high precision simulations are required to determine the ground state energy from the small- x asymptote. In particular, our simulated data did not even allow the computation of the ground state energy to within a factor of 2 for the case of $\alpha=2$ where the lowest eigenvalue is known.

X. MRH DISTRIBUTION FOR LARGE α

We have calculated the MRH distribution for the $\alpha \rightarrow \infty$ limit in Sec. V. There we found that only the $n=1$ mode survives and, as a result, the PDF (20) emerges. Here we discuss a procedure for perturbatively computing the leading corrections to Eq. (20) by taking into account the modes $n=2, 3, \dots$.

First we reiterate that the amplitude of modes c_n obey the distribution with action (3) and measure proportional to $\prod_n \theta(c_n) c_n dc_n$. Thus, separating the $n=1$ mode, the path in Fourier representation is written as

$$h(t) = a_1 \sin(t) + \sum_{n=2}^{\infty} \varepsilon_n a_n \sin(nt + \varphi_n), \quad (66)$$

where the $\varepsilon_n = 1/n^{\alpha/2}$ is the mean square root deviation of the amplitude of the n th mode, and the $a_n = c_n/\varepsilon_n$'s are i.i.d. variables distributed according to

$$P_0(z) = 2z\theta(z)\exp(-z^2). \quad (67)$$

Finally the phases φ_n are independent and uniformly distributed in $[0, 2\pi]$. The $n=0$ phase is omitted, because the choice of the origin is arbitrary. Obviously, x measures the height from the time average of the path, which is here set to zero. Note that now time t is in units of $2\pi/T$.

The leading correction from higher frequency modes can be calculated independently for each mode, thus here we only consider the n th mode. Then the path is

$$h(t) = a_1 \sin(t) + \varepsilon_n a_n \sin(nt + \varphi_n) \quad (68)$$

and the calculation to leading order is straightforward. We compute the maximum of the path and then, knowing the distribution of all parameters therein, we can determine the PDF of the maximum. The details are presented in Appendix B, where we obtain the perturbed PDF for $h_m T^{(1-\alpha)/2} = z$ as

$$P(z) = P_0(z) + \varepsilon_n^2 P_{2,n}(z), \quad (69)$$

with

$$P_{2,n}(z) = (1 - n^2/2) \delta(z) + z \delta'(z)/2 + e^{-z^2} \theta(z) [2z^3 + (n^2 - 3)z]. \quad (70)$$

The singular part needs some explanation here. As has been discussed in Sec. IX, for finite α 's the PDF starts nonanalytically with zero initial slope for finite α 's, in contrast to the $\alpha=\infty$ case, where the PDF has a finite slope. The nonanalyticity is not expected to be recovered by any expansion. Nonetheless, the formal expansion gives an explicit correction function $P_{2,n}$, with delta singularity at the origin. It is plausible to conclude that while the expansion cannot be correct overall, the singularity "tries" to take care of the nonanalytic difference in the small- z behavior, while the nonsingular part is expected to be a faithful correction for $z > 0$. This leaves open the possibility that the large α expansion is not convergent, rather it is asymptotic.

Next we scale the PDF to unit average. Using the result (B8) from Appendix B one finds

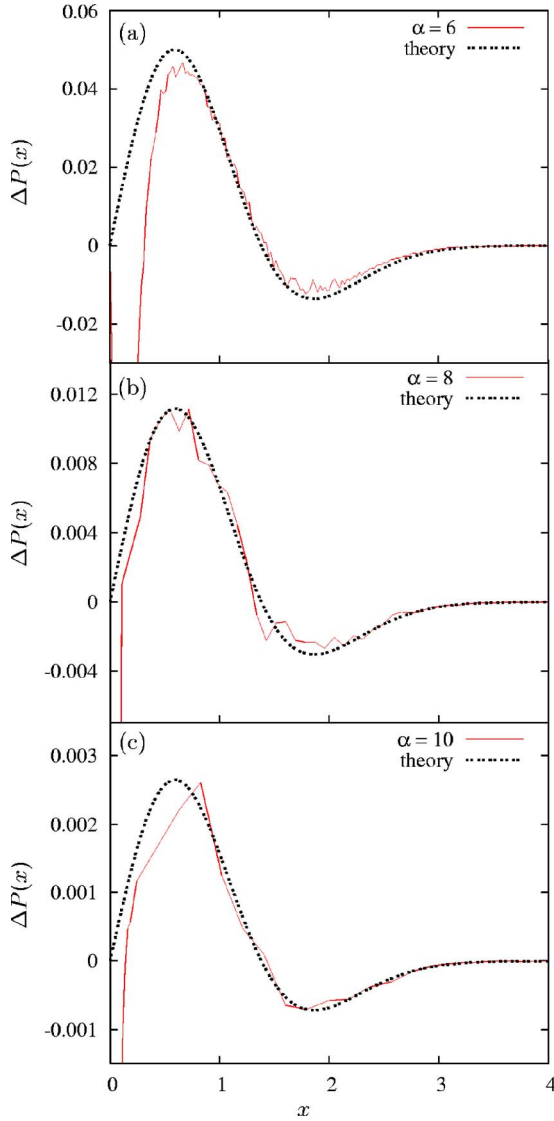


FIG. 8. (Color online) Difference $\Delta P(x)$ between the MRH distribution for large α and $\alpha=\infty$, as defined in Eq. (73). We also display the smooth part of the leading correction (74) from perturbation theory added up from the modes $n=2,3$.

$$\Phi(x) = \Phi_\infty(x) + \varepsilon_n^2 \Phi_{2,n}(x) \quad (71)$$

where $\Phi_\infty(x)$ is given in Eq. (20) and

$$\begin{aligned} \Phi_{2,n}(x) = & (1 - n^2/2)\delta(x) + x\delta'(x)/2 \\ & + e^{-\pi x^{2/4}}\theta(x)\frac{\pi}{8}(n^2 - 1)(6x - \pi x^3). \end{aligned} \quad (72)$$

Formally, we can sum up the leading corrections for all n 's. However, this is not a consistent approximation, because, for instance, $\varepsilon_2^2 = \varepsilon_4$, so the leading correction from $n=4$ is of the same order as the quadratic one from $n=2$. Therefore we use the sum of the corrections for only $n=2,3$ to test the prediction. On Fig. 8 we display the correction

$$\Delta\Phi(x) = \Phi(x) - \Phi_\infty(x) \quad (73)$$

of the PDF from simulation for a series of α 's, together with the theoretical prediction for corrections added up from the modes $n=2,3$,

$$\Delta\Phi(x) \approx \varepsilon_2^2 \Phi_{2,2}(x) + \varepsilon_3^2 \Phi_{2,3}(x). \quad (74)$$

It should be mentioned that the sum of leading corrections for all modes has a prefactor $\sum_{n=2}^{\infty} (n^2 - 1)\varepsilon_n^2 = \zeta(\alpha - 2) - \zeta(\alpha)$. This diverges for $\alpha \rightarrow 3^+$, so the series does not converge for $\alpha \leq \alpha_c = 3$, which is the borderline for the differentiability of the path. We cannot exclude that higher order corrections, involving higher order differentiation of the path, further tighten the range of convergence.

XI. COMPARISON WITH THE ROUGHNESS AND THE MAXIMAL INTENSITY

Here we compare the statistical properties of h_m to those of the roughness w_2 , i.e., of the mean square deviation, or width of the trajectory (7). The latter was one of the first global quantities of stochastic signals whose scaling properties and statistics were extensively studied for $1/f^\alpha$ processes [28].

One of the reasons for comparison is that both $\langle h_m \rangle$ and $\sqrt{\langle w_2 \rangle}$ scale similarly with T for $\alpha \geq 1$ and, furthermore, there are many common features at the level of their PDFs. Namely, for $\alpha > 1$, after scaling by the mean, the PDFs are nondegenerate (each cumulant is finite), that is, scaling by the mean is a natural representation of both PDFs. As $\alpha \rightarrow 1$, the PDFs scaled by the mean approach a Dirac delta and, in the range $\alpha \leq 1$, they both lend themselves to scaling by the standard deviation. Here an important difference emerges. In the range $0.5 < \alpha \leq 1$ the roughness has a non-trivial PDF while below the critical $\alpha=0.5$ it becomes trivial, i.e., the roughness becomes Gaussian distributed. On the other hand, the MRH has the trivial FTG limiting distribution in the entire $0 < \alpha < 1$ region. We can only speculate that the threshold near $\alpha=0.5$ manifests itself in the MRH distribution in its approach to the FTG limit, as suggested by the finite-size dependence of the simulation results shown in Fig. 3. This, however, is just a numerical observation without theoretical foundations as yet.

Further motivation for a closer comparison comes from the similarities in the shape of the two families of PDFs in the $\alpha > 1$ region. First, in the $\alpha \rightarrow \infty$ limit, the PDFs are the same if the $h_m \sim \sqrt{w_2}$ correspondence is made. Second, for finite α 's, the unimodal PDFs have asymptotes which are similar for both small and large arguments. Specifically, there is a Gaussian decay at large x , while the small x behavior is dominated by an exponential nonanalytic term with a power prefactor. Here, the comparisons can be made quantitatively for small x , since analytic results are available for general α .

Last but not least, a reason for a closer comparison comes from the fact that the roughness can also be conceived as obeying an EVS. Bertin and Clusel [13,49] made the remarkable observation that since the roughness is essentially the integrated power spectrum, i.e., the sum of nonnegative Fourier intensities, it is in effect the maximum of positive partial

sums. In general, the partial sums are correlated but, for the special case of $\alpha=1$, they correspond to the ordered sequence of i.i.d. variables. As a consequence, FTG distribution emerges for w_2 at $\alpha=1$, thus providing insight to an earlier rather puzzling result [9] in connection with $1/f$ noise. It then becomes a rather interesting open question how the MRH distribution differs from the roughness distribution for $\alpha>1$ where the latter also describes the EVS of correlated variables.

The initial asymptote of the MRH distribution (62) and (63) should be compared with that for the roughness distribution obtained in Appendix E of [10]

$$\Phi_w(x) \approx C_w x^{-\gamma_w} \exp(-B_w/x^{\beta_w}), \quad (75)$$

where the parameters are given by

$$\beta_w = \frac{1}{\alpha - 1}, \quad (76a)$$

$$\gamma_w = \frac{3\alpha - 1}{2(\alpha - 1)}, \quad (76b)$$

$$B_w = (\alpha - 1) \left(\frac{\pi}{\alpha \sin(\pi/\alpha)} \right)^{\alpha/(\alpha-1)} \zeta(\alpha)^{-1/(\alpha-1)}, \quad (76c)$$

$$C_w = \frac{(2\pi)^{(\alpha-1)/2}}{\sqrt{\alpha-1}} \left(\frac{\pi}{\sin(\pi/\alpha)} \right)^{\alpha/(\alpha-1)} [\zeta(\alpha)\alpha]^{-(\alpha+1)/2(\alpha-1)}, \quad (76d)$$

with $\zeta(\alpha)$ denoting the Riemann's zeta function. Note that this asymptote does not contain unknown parameters such as ϵ_0 in the MRH distribution.

Interestingly, comparison with the exponents in the asymptote of the MRH, Eq. (62), shows that the respective γ 's are the same, if $\sqrt{w_2}$ is considered, i.e., $2\gamma_w = \gamma$. Nevertheless, the respective exponents in the prefactor, $2\beta_w + 1$ and β , agree only at an accidental α and are otherwise different.

The present results on the small- x asymptote may also be compared to the asymptote of the distribution of the maximal Fourier intensity. It is defined as the maximal of the $|c_n|^2$ intensity components for a given realization of the path, which obeys some PDF if the ensemble of $1/f^\alpha$ paths is considered. This was to our knowledge the first quantity whose EVS was studied in the context of $1/f^\alpha$ signals [10]. Again, the overall shape of the PDF of the extremal intensity is similar to those of the MRH and the roughness: Its initial part is suppressed nonanalytically and has a single maximum, before smoothly decaying for large arguments. There the critical α_c where the FTG limit distribution emerges is $\alpha_c=0$, in contrast to the MRH and the roughness, where the critical values are $\alpha_c=1$ and $\alpha_c=0.5$, respectively. As we have shown in [10], written with α_c , the powers in the asymptotic formula for the maximal intensity and for the roughness are the same

$$\beta_w = \beta_I = \frac{1}{\alpha - \alpha_c}, \quad \gamma_w = \gamma_I = \frac{3(\alpha - \alpha_c) + 2}{2(\alpha - \alpha_c)}, \quad (77)$$

where the exponents β_I, γ_I are defined in the same way for the initial asymptote of the PDF of the maximal intensity as β_w, γ_w were for the PDF of the roughness.

In conclusion, the respective PDFs of the MRH, the maximal intensity, and the roughness are similarly looking, unimodal functions, with nonanalytically slow initial behavior. Despite the qualitative similarities, however, it is clear that the three PDFs are quantitatively different. This is natural since they describe different physical quantities. One may, however, speculate that the similar features have their roots in the divergent correlations present in the $\alpha \geq 1$ region.

XII. FINAL REMARKS

It should be emphasized that we are only at the first stages of understanding the effects of correlations on EVS. One of the important tasks for future studies should be the understanding of the convergence properties in the $0 < \alpha < 1$ range. Although the limit distribution is known here, the convergence is extremely slow. Since most of the environmental time series of general interest (data on temperature, precipitation, etc.) correspond to this range, as they exhibit generically correlations with power-type decay, and the length of the series is naturally restricted, the development of a theory of finite-size corrections is important. The much discussed $\alpha \rightarrow 1$ case is even more challenging since it appears to be outside the reach of present computing abilities. Thus new analytical approaches and ideas for numerical recipes are called for.

Another relevant problem is the question of boundary conditions. It is known from the $\alpha=2$ case, where both periodic and free boundary conditions were investigated [7], that the MRH distribution depends on boundary conditions. Since the analysis of a real time series usually means cutting it up into smaller pieces and making statistics out of the properties of these subsequences, the appropriate boundary conditions in this case are the so-called window boundary conditions, when the window under consideration is embedded in a longer signal. These boundary conditions have been discussed in connection with the roughness distribution of $1/f^\alpha$ signals [28]. It has been found that the limit distributions depend on the window size (with respect to the length of the entire system) and furthermore, the effects become stronger as α increases. Clearly, similar studies should be carried out for the EVS problem.

Finally, it remains to be seen if the investigations of the effects of correlations, in particular the effects of strong correlations, will allow us a universal classification of EVS similar to that existing for thermodynamic critical points.

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APPENDIX A: DERIVATION OF THE PROPAGATOR FOR $\alpha=2n$

Here we show that the ansatz (27) indeed satisfies the Fokker-Planck equation (25) with the coefficients (28a)–(28c). Let us start out from Eq. (25)

$$\partial_t G_n = \frac{1}{2} \partial_1^2 G_n - \sum_{k=1}^{n-1} z_k \partial_{k+1} G_n, \quad (\text{A1})$$

and substitute

$$G_n = G_{n-1} \mathcal{G}, \quad (\text{A2})$$

where the arguments are understood as in Eq. (27). Using the fact that G_{n-1} also satisfies Eq. (A1), we arrive at

$$\partial_t \mathcal{G} = \frac{1}{2} \partial_1^2 \mathcal{G} + \partial_1 \mathcal{G} \partial_1 \ln G_{n-1} - \sum_{k=1}^{n-1} z_k \partial_{k+1} \mathcal{G}. \quad (\text{A3})$$

From Eq. (27) we have

$$\partial_k \mathcal{G} = a_k^n \mathcal{G}', \quad (\text{A4a})$$

$$\partial_k^2 \mathcal{G} = (a_k^n)^2 \mathcal{G}'', \quad (\text{A4b})$$

where, denoting $\mathbf{a}^n \cdot \mathbf{z} - \mathbf{a}^{0,n} \cdot \mathbf{z}^0$ by x ,

$$\mathcal{G}'(x; \sigma) = -\frac{x}{\sigma^2} \mathcal{G}(x; \sigma), \quad (\text{A5a})$$

$$\mathcal{G}''(x; \sigma) = -\frac{\mathcal{G}(x; \sigma)}{\sigma^2} - \frac{x}{\sigma^2} \mathcal{G}'(x; \sigma), \quad (\text{A5b})$$

and, furthermore, using the full exponent of the ansatz (26) we have

$$\partial_1 \ln G_{n-1} = -\sum_{k=1}^{n-1} \frac{a_1^k}{\sigma_k^2} (\mathbf{a}^k \cdot \mathbf{z} - \mathbf{a}^{0,k} \cdot \mathbf{z}^0). \quad (\text{A6})$$

Differentiation of the Gaussian \mathcal{G} by time gives

$$\begin{aligned} \partial_t \mathcal{G} = & -\frac{1}{2} \frac{\sigma_n^2}{\sigma_n^2} \mathcal{G} - \frac{1}{2} \frac{\sigma_n^2}{\sigma_n^2} (\mathbf{a}^n \cdot \mathbf{z} - \mathbf{a}^{0,n} \cdot \mathbf{z}^0) \mathcal{G}' \\ & + (\dot{\mathbf{a}}^n \cdot \mathbf{z} - \dot{\mathbf{a}}^{0,n} \cdot \mathbf{z}^0) \mathcal{G}', \end{aligned} \quad (\text{A7})$$

where we have condensed some z dependence by factoring out \mathcal{G}' . On the other hand, according to Eqs. (A4) and (A5), the right-hand side of Eq. (A3) yields

$$\begin{aligned} \partial_t \mathcal{G} = & -\frac{1}{2} (a_1^n)^2 \left(\frac{\mathcal{G}}{\sigma_n^2} + \frac{\mathbf{a}^n \cdot \mathbf{z} - \mathbf{a}^{0,n} \cdot \mathbf{z}^0}{\sigma_n^2} \mathcal{G}' \right) \\ & - a_1^n \mathcal{G}' \sum_{k=1}^{n-1} \frac{a_1^k}{\sigma_k^2} (\mathbf{a}^k \cdot \mathbf{z} - \mathbf{a}^{0,k} \cdot \mathbf{z}^0) - \sum_{k=1}^{n-1} z_k a_{k+1}^n \mathcal{G}'. \end{aligned} \quad (\text{A8})$$

Equating Eq. (A7) with Eq. (A8) should give the sought after

equations for \mathbf{a} , \mathbf{a}^0 , and σ . Comparing the z -independent factors of \mathcal{G} in Eqs. (A7) and (A8) gives

$$\dot{\sigma}_n^2 = (a_1^n)^2. \quad (\text{A9})$$

Thus the full first lines on the right-hand side of Eqs. (A7) and (A8) are equal. In the rest we change the summation variable k to l and then equate the respective factors of z_k and those of z_k^0 to obtain differential equations for the coefficients

$$\dot{a}_k^n = -a_1^n \sum_{l=k}^{n-1} \frac{a_1^l a_k^l}{\sigma_l^2} - a_{k+1}^n, \quad (\text{A10a})$$

$$\dot{a}_k^{0,n} = -a_1^n \sum_{l=k}^{n-1} \frac{a_1^l a_k^{0,l}}{\sigma_l^2}, \quad (\text{A10b})$$

where we have used the condition that $a_k^l = a_k^{0,l} = 0$ for $k > l$. Next, we determine the time dependence of the a 's by assuming it to be power law and requiring that terms in each differential equation have the same power. Thus we separate the time dependence, and for later purposes also factorize the constants as

$$a_k^n = t^{n-k} b_k^n c_n, \quad a_k^{0,n} = t^{n-k} b_k^{0,n} c_n, \quad (\text{A11})$$

for all nonnegative integers n, k . We also set $b_k^n = 0$ for $n < k$ to ensure that a_k^n vanishes for such indices. The c_n 's are made unambiguous by requiring $b_1^n = 1$ and, furthermore, since $a_n^n = 1$ thus $b_n^n = 1/c_n$. Then Eq. (A9) gives

$$\sigma_n^2 = (c_n)^2 \frac{t^{2n-1}}{2n-1}. \quad (\text{A12})$$

The parametrization in Eq. (A11) is justified by the fact that substituting it into Eq. (A10) the c 's disappear, so what remains are equations for the b 's as

$$b_{k+1}^n = -(n-k) b_k^n - \sum_{l=k}^{n-1} (2l-1) b_k^l, \quad (\text{A13a})$$

$$b_k^{0,n} = -\frac{1}{n-k} \sum_{l=k}^{n-1} (2l-1) b_k^{0,l}. \quad (\text{A13b})$$

For a few small integer indices these equations can be solved; whence the following general formulas can be surmised:

$$b_k^n = (-1)^{k-1} \frac{(n+k-2)!}{(n-k)! (k-1)!}, \quad (\text{A14a})$$

$$b_k^{0,n} = (-1)^{n-k} b_k^n. \quad (\text{A14b})$$

Note that Eqs. (A13a) and (A13b) are homogeneous linear equations leaving room for overall factors in the solution. They are set by the conditions (i) $b_1^n = 1$ and (ii) $b_n^{0,n} = b_n^n$. Condition (i) was stated earlier below Eq. (A11), while (ii) is equivalent to the requirement that G_n depends on z_n and z_n^0 only through their difference.

One can confirm proposition (A14) by substituting it into Eq. (A13) and then using the identities

$$\sum_{l=k}^{n-1} \frac{(2l-1)(k+l-2)!}{(l-k)!} = \frac{n-1}{k} \frac{(n+k-2)!}{(n-k-1)!}, \quad (\text{A15a})$$

$$\sum_{l=k}^{n-1} (-1)^l \frac{(2l-1)(k+l-2)!}{(l-k)!} = (-1)^{n+1} \frac{(n+k-2)!}{(n-k-1)!}, \quad (\text{A15b})$$

which may be proved by induction.

Finally, with Eq. (A14) together with

$$c_n = \frac{1}{b_n^n} = \frac{1}{(-2)^{n-1}(2n-3)!!} \quad (\text{A16})$$

we have all ingredients of Eq. (A11) to calculate the a 's, the result being displayed in Eq. (28). The standard deviation σ_n given in Eq. (28) follows then from Eqs. (A12) and (A16).

APPENDIX B: LEADING PERTURBATION OF THE PDF FOR LARGE α FROM THE n TH MODE

We start out from the Fourier representation (68) of the path with one mode of frequency n beside the basic one ($n=1$). From the condition $h'(t_0)=0$, we obtain the correction in the position $t_0=\pi/2+\delta_n$ of the maximum to leading order

$$\delta_n = n\varepsilon_n \frac{a_n}{a_1} \cos\left(\frac{n\pi}{2} + \varphi_n\right). \quad (\text{B1})$$

Hence we can calculate the maximum to second order in ε_n (the quadratic correction in δ_n contributes only to cubic order)

$$\begin{aligned} h_m &= h(t_0) \approx h(\pi/2) + h'(\pi/2)\delta_n + 1/2h''(\pi/2)\delta_n^2 \\ &\approx a_1 + \varepsilon_n a_n \sin\left(\frac{n\pi}{2} + \varphi_n\right) \\ &\quad + \frac{n^2\varepsilon_n^2 a_n^2}{2a_1} \cos^2\left(\frac{n\pi}{2} + \varphi_n\right). \end{aligned} \quad (\text{B2})$$

Now the PDF for the MRH h_m is obtained by averaging over a_1, a_n, φ_n in

$$P(z) = \langle \delta(z - h_m) \rangle. \quad (\text{B3})$$

Expanding to second order, one finds

$$\begin{aligned} P(z) &= \langle \delta(z - a_1) \rangle - \left\langle \delta'(z - a_1) \left[\varepsilon_n a_n \sin\left(\frac{n\pi}{2} + \varphi_n\right) \right. \right. \\ &\quad \left. \left. + \frac{n^2\varepsilon_n^2 a_n^2}{2a_1} \cos^2\left(\frac{n\pi}{2} + \varphi_n\right) \right] \right\rangle \\ &\quad + \frac{\varepsilon_n^2}{2} \left\langle \delta''(z - a_1) a_n^2 \sin^2\left(\frac{n\pi}{2} + \varphi_n\right) \right\rangle. \end{aligned} \quad (\text{B4})$$

Note that here derivatives of the Dirac delta appear. Now performing the averages yields [P_0 is given by Eq. (67)]

$$P(z) = P_0(z) + \varepsilon_n^2 P_{2,n}(z), \quad (\text{B5})$$

$$P_{2,n}(z) = -\frac{n^2}{2} (\theta(z)e^{-z^2})' + \frac{1}{2} (\theta(z)ze^{-z^2})''. \quad (\text{B6})$$

Differentiation of the terms with step functions gives

$$P_{2,n}(z) = (1 - n^2/2) \delta(z) + z \delta'(z)/2 + e^{-z^2} \theta(z) [2z^3 + (n^2 - 3)z], \quad (\text{B7})$$

where the term proportional to $z^2\delta(z)$ has been omitted, since it does not contribute to the average and other moments of nonsingular functions. Hence we obtain formula (70).

The mean to second order is best calculated from Eqs. (B5) and (B6) resulting in

$$\langle z \rangle = \frac{\sqrt{\pi}}{2} + \varepsilon_n^2 \frac{n^2 \sqrt{\pi}}{4}. \quad (\text{B8})$$

The scaled PDF is then obtained by the change of variable from z to $x=z/\langle z \rangle$, and expanding the resulting expression to second order in ε_n yields Eqs. (71) and (72).

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